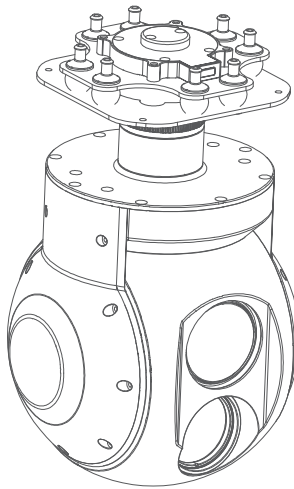
UA40T-35 40x EO+IR Dual Sensors AI Object Tracking Gimbal Camera

User Manual



For more details please scan the QR code or visit our website:
www.viewprotech.com

Warning

Thank you for purchasing Viewpro product. Please read this user manual carefully to make sure the correct operation of this product. Failure to follow instructions and operate in accordance with the instruction in this user manual may damage the product. Do not disassemble or assemble the product by yourself, otherwise it may be damaged or not work properly. Viewpro has no ability for any damage that caused by users' incorrect operation, installation and reassembling in directly or indirectly.

Warning Signs



Warning



Important Note

Important Notes

1. After using the product, please keep the device in dry environment to avoid fogging the lens due to excessive ambient humidity. If the lens fogs, turn on the camera for a while and wait for the fog to dissipate.

2. When using the in frared thermal lens, do not aim at strong energy sources, such as the sun, laser beams, lava, etc. The temperature of the measured target must be less than 800°C, otherwise the lens will be burned and cause irreversible damage.

3. When cleaning the dirty on surface of lens, make sure the cleaning cloth is soft and dry.

4. Do not directly touch or scratch the coating on the surface of the infrared lens with your hands or hard objects, otherwise the coating will be damaged and cause blurred image.

5. Do not plug or unplug the TF card when power on; after plugging and unplugging the TF card, please make sure that the TF rubber plug is tightly covered to prevent the poweron self-check from failing.

1. Product Introduction

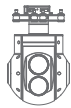
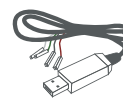
1.1 Introduction

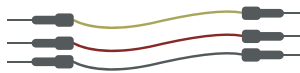
UA40T-35 is a 2-axis high-precision gimbal camera with 40x optical zoom COMS sensor which adopts a 2.13MP high resolution EO sensor, and a resolution of 640*512 35mm lens uncooled long wave IR thermal imager sensor. It supports optical zoom, photographing and video, target tracking, thermal digital zoom and AI auto recognition of vehicle and human.

It features with aluminum alloy housing and anti-interference. The 3 axis gimbal can achieve stabilization in yaw, roll and pitch. Integrated with damping system, gimbal can greatly reduce mechanical vibration to stabilize image.

UA40T-35 is widely used in UxS industries of public security, electric power, fire fighting, zoom aerial photography and other industrial applications.

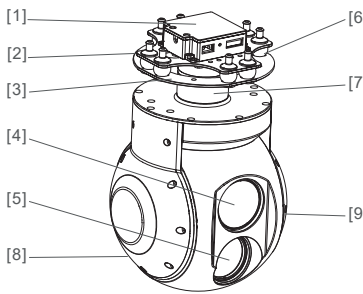
1.2 Packing List

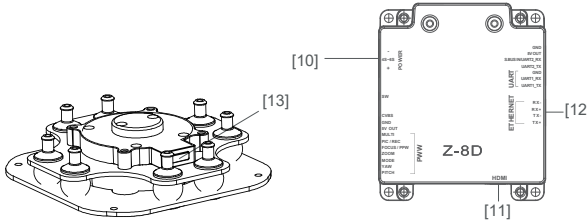
Gimbal (Standard Version) ×1		Gimbal (Viewport Version) ×1	
Aluminum Cylinder ×4		USB to TTL line ×1	
M3 screw ×8			

Power Line ×1	
PWM Control line ×1	
Serial port/S.bus Control lin ×1	
Connect serial port line ×3	
Ethernet line ×1	

2. Installation Instruction

2.1 Overview





Viewport

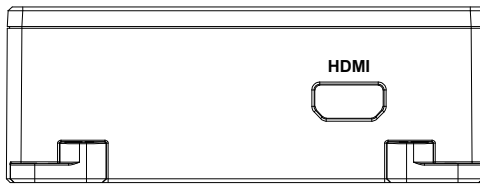
Control Box

[1] Control box
[2] Upper damping board
[3] Lower damping board
[4] FHD zoom camera
[5] Infrared thermal camera
[6] Damping ball
[7] Yaw axis motor
[8] TF card slot
[9] Pitch axis motor
[10] 4-6S power interface
[11] Micro HDMI interface
[12] Ethernet interface
[13] Viewport unlock button

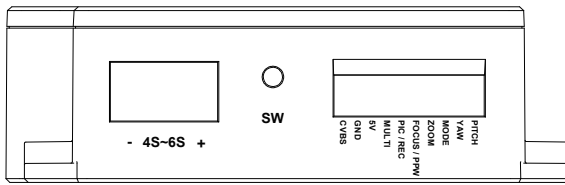
- Make sure no obstacle while the motor is rotating.
- Don’t put the thermal imager face to heat or straight to the sun.

2.2 Control Box Printing

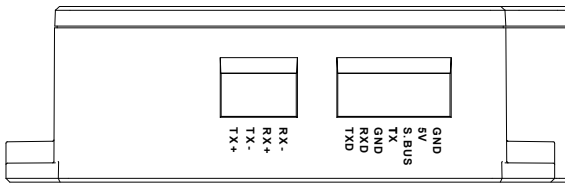
Front Side



Left Side

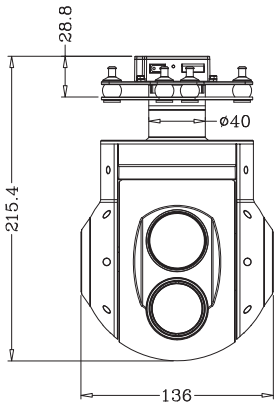


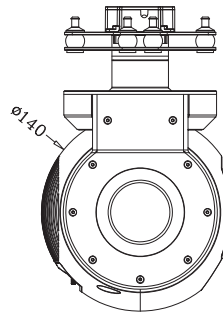
Right Side

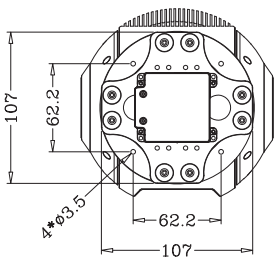


2.3.1 Device Dimensions (Standard Version)

Unit: mm

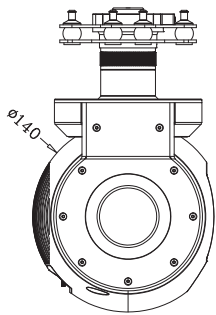


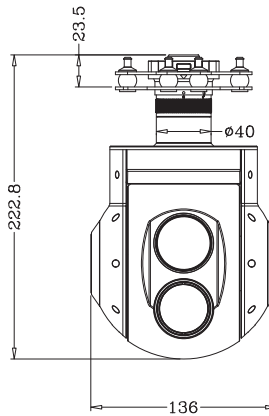


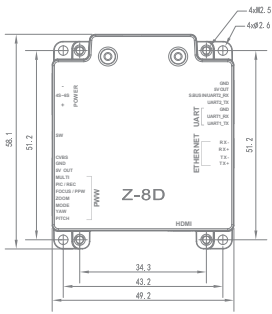


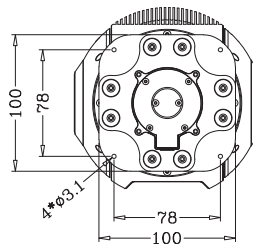
2.3.2 Device Dimensions (Viewport Version)

Unit: mm









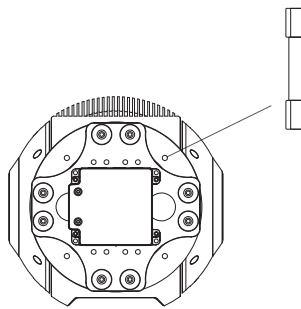
Control Box

2.4 Install Mounting Part

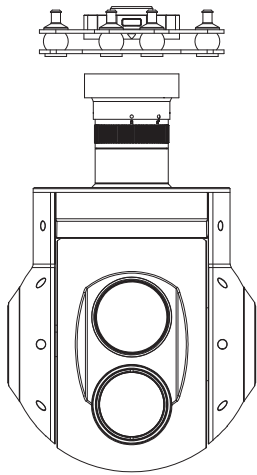
(1) Find out the arrow icon on the gimbal (that is the lens direction when camera is power on) , and keep its direction same as the specified direction of UxS.

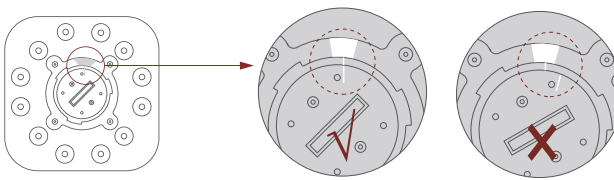
(2) Fix one end of the Aluminum Cylinder on the screw hole of lower damping board, and use M3 screw to fasten it.

(3) According to the provided screw hole dimension and the actual situation, the user can add suitable mounting holes on the UxS mounting board, and fixes the other end of the Aluminum Cylinder on the mounting board of the UxS (Viewport version is the same).

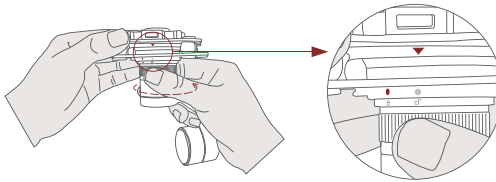


2.5 Viewport Release Instruction

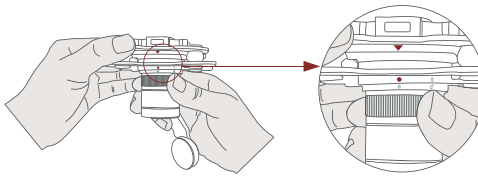




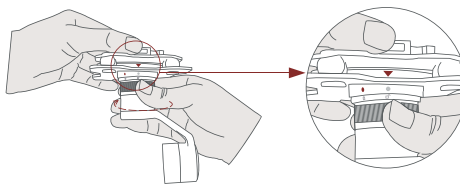
1.Make sure the two white stripes indicated in above picture are aligned with each other. If not aligned, please adjust it manually.



2. Align the white dot (unlock icon) to the red triangle (below unlock button), push the gimbal into the Viewport completely and then rotate the gimbal camera counter-clockwise.



3.When you hear a "click" sound (red dot is aligned to the red triangle) means that the gimbal camera and Viewport has been locked.



4.To unlock the Viewport, you need to press on unlock button and rotate the gimbal camera clockwise till the white dot align to the red triangle. Then pull the gimbal out from the Viewport.

2.6 Install TF Card

TF (Micro SD card):

Insert the TF card to the card slot (Re. 2.1 Overview). It support maximum capacity of 256GB, and require Class 10 (10m/s) transmission speed or higher and FAT32 format.



- The hot plugging is not supported.
  Make sure power is off when inserting the TF card.

2.7 Image Output Interface

HDMI output: Micro HDMI port, supports 1080P@60fps, connects to external monitors or video transmitters for real-time preview.

Network output: Standard RJ45 port, supports RTSP/UDP/RTMP. Default: RTSP, stream at rtsp://192.168.2.119:554, 720P@30fps, 2Mbps bitrate . All parameters user-adjustable.

Analog output: not supported.



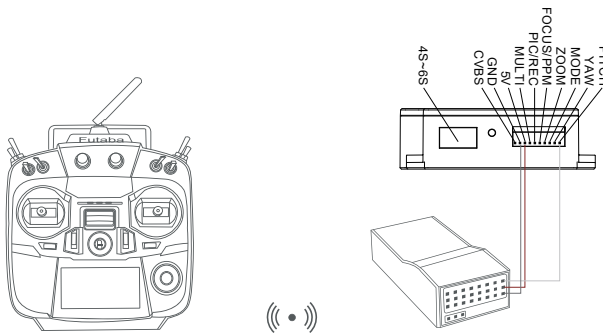
- Video output varies by model, refer to actual product. Due to 360° continuous yaw rotation, this gimbal series does not support HDMI. And SDI and HDMI are mutually exclusive and cannot be configured together on the same device.
- When using user interface software Viewlink for network connection, the network of external device (computer) should be the IP address: 192.168.2.2 (choose the last byte among 2~254, but must not be 119 same as the gimbal), subnet mask: 255.255.255.0, Default gateway: 192.168.2.1, and all firewalls of the computer must be turned off. Then enter the IP address of the gimbal camera, Open Video, the video stream can be output.

3. Signal Control

3.1 PWM Control

Control the functions of gimbal camera through the multiplex pulse width modulation signal outputted by PWM channel of the remote control receiver. The gimbal camera needs 7 control channels of PWM at most. Users can choose the required function channels, and reduce some PWM channels accordingly in usage.

PWM Connection Diagram (Connect pitch channel as an example)



Remote Controller

Receiver

Connection Diagram

PWM Control Operation Instruction

3.1.1 Pitch Channel: Connect PWM Pitch channel to control Pitch by Joystick, rotary knob and 3-gear switch on remote control. Take 3-gear switch as an example.



Position 1

Low Gear
Pitch Up



Position 2

Middle Gear
Pitch Stop



Position 3

High Gear
Pitch Down

3.1.2 Yaw Channel: Connect PWM Yaw channel to control Yaw by Joystick, rotary knob and 3-gear switch on remote control. Take 3-gear switch as an example.



Position 1

Low Gear
Yaw Left



Position 2

Middle Gear
Yaw Stop



Position 3

High Gear
Yaw Right

3.1.3 Mode Channel: Connect PWM Mode channel to adjust speed control and One-key to Center. Take 3-gear switch as an example.



Position 1

Low Gear



Position 2

Middle Gear



Position 3

High Gear

Switch position 1: Low speed mode, control pitch / yaw to move at lowest speed;
Switch position 2: Middle speed mode, control pitch / yaw to move at middle speed;
Switch position 3: High speed mode, control pitch / yaw to move at highest speed.
(When it is controlled by rotary knob, the speed will change according to switch position)

Function of continuous switch:

1.Switch one time from position 2 - 3 quickly, to Home position.
2.Switch twice from position 2 - 3 - 2 - 3 continuously and quickly, the camera lens is positioned vertically downward.
3.Switch 3 times from position 2 - 3 - 2 - 3 - 2 - 3 continuously and quickly, to close Follow Yaw Mode.
4.Switch 4 times from position 2 - 3 - 2 - 3 - 2 - 3 - 2 - 3 continuously and quickly, to start Follow Yaw Mode.

3.1.4 Zoom Channel :Connect PWM zoom channel to control Zoom by Joystick, rotary knob and 3-gear switch on remote control. Take 3-gear switch as an example.



Position 1

Low Gear
Zoom Out



Position 2

Middle Gear
Stop Zoom



Position 3

High Gear
Zoom In

3.1.5 Focus Channel: Connect PWM Focus channel to control PIP and IR color palette switch by 3-gear switch. Take the 3-gear switch as an example.
Switch from Position 2 to 1: turn to Picture in Picture mode and four display mode (IR、IR+EO、EO、EO+IR) switch cyclically.
Switch from Position 2 to 3: Three types of IR color (black hot, white hot, pseudo color)switch cyclically.



Position 1

Low Gear
PIP switch



Position 2

Middle Gear
No control



Position 3

High Gear
IR color palette switch

3.1.6 Pic/Rec Channel: Connect PWM Pic/Rec channel to control “Photograph” and “Record” by, rotary knob or 3-gear switch on remote control. Take 3-gear switch as an example.)



Position 1

Low Gear



Position 2

Middle Gear



Position 3

High Gear

Switch from Position 2 to 1 to take a picture.
OSD display “IMG PHOTOING” at the left top corner and the picture is stored in TF card.

Switch from Position 2 to 3 to start “ Record ” , and repeat the operation to stop recording.
During recording, OSD display information of “REC 00 00 00”, as current recording time, and the remaining capacity of TF card. It will show the “TFXXXMB” when stop recording. When the storage capacity of TF card is full , “TF FULL” is shown on screen. If no TF card is inserted, “ NO TF” is shown on screen. Please insert the TF card before using.

3.17 Multi Channel: Connect Multi Backup channel to control digital zoom and tracking by 3-gear switch on the remote control. Take 3-gear switch as an example.



Position 1

Low Gear



Position 2

Middle Gear



Position 3

High Gear

Switch from Position 2 to 1: Thermal imager digital zoom, 1X,2X, 3X, 4X.
Switch from Position 2 to 3: Display the tracking box at the center of screen, start tracking.
Switch from Position 3 to 2: Cancel tracking.

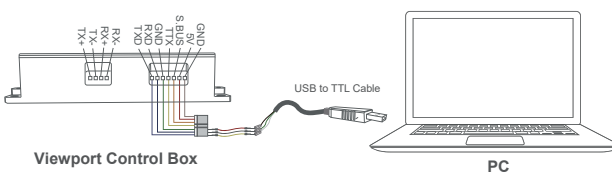
3.2 Serial Port / TTL Control

TTL communication requirements: TTL signal is 3.3V, baud rate: 115200, data bit 8, stop bit 1, no parity, HEX send and receive.

Connection Diagram (PC - USB to TTL Cable- Gimbal Camera as an example):

Gimbal Camera **Cable**

TX ⟷ RX (White)
RX ⟷ TX (Green)
GND ⟷ GND (Black)



Connection Diagram

Diagram of USB to TTL Cable:

Connect the camera to the upper computer by USB to TTL cable (Adopt connection method of TX to RX, RX to TX, GNG to GND at Dupont ends of the provided USB to TTL cable, connect to the specified TTL of the gimbal, and the USB end of the cable connect to computer).

Install Viewlink control software to test the functions directly. Users may choose to develop their own software, please contact technical support for TTL control protocol file.

ViewLink is a user interface developed by Viewpro for Viewpro gimbal cameras, you can download it from Viewpro website (www.viewprotech.com) or ask distributors for installation package.

- Connect serial port of gimbal to pins, DO NOT connect with power supply.
- The default baud rate of serial port is 115200, which can be changed according to the docking equipment.

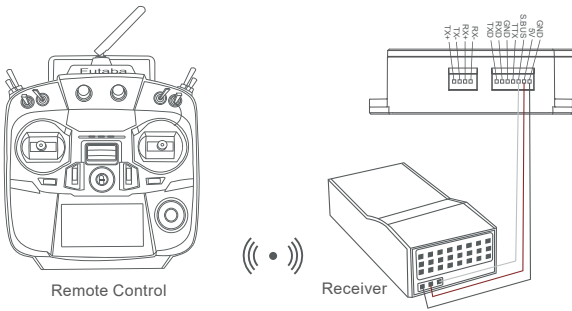
3.3 S.BUS Control

Control the gimbal camera functions by one combining signals. Connect the external S.Bus to S.Bus port on the control box, and the external S.bus signal GND connect to the GND interface of the control box.

Take Futaba's S.Bus remote control for example:

Connect receiver's S.Bus port with gimbal camera. The receiver working power (5V) is supplied from gimbal camera.

Wiring Diagram (Take Futaba remote control for example):



Wiring Diagram

S.Bus control mode: default S.Bus signal channel 7-13 to control gimbal camera functions (the function of channel is consistent with the corresponding channel in PWM function description)

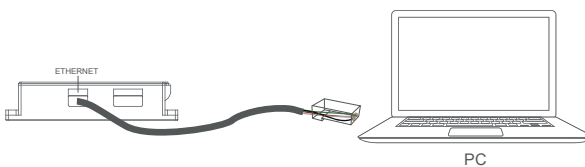
Channel7: Yaw Control
Channel 8: Pitch Control
Channel 9: Mode Control
Channel 10: Zoom Control
Channel 11: Focus Control
Channel 12: Pic/Rec Control
Channel 13: Multi Backup

- User can set the channels by setting serial command according to the actual requirement. The S.Bus channel position can be arranged in any sequence within channel 7-13 to connect with the flight controller or remote control.
- TTL control and S.bus control cannot coexist at the same time for standard version. The defualt control is TTL if no requirement. The user can set to S.bus control if needed (please contact with our technical support for the setting instruction.)

3.4 TCP control

For Viewpro gimbal cameras with Ethernet output, the default IP address is: 192.168.2.119, control port: 2000. You can send the corresponding protocol to realize TCP control after connecting.

The TCP control protocol is [Frame header: EB + command ID: 90 + data body (serial port protocol) + Checksum (CS = body checksum, checksum is calculated as a sum of all bytes of data body modulo 256)]. Or directly use UI Viewlink to control after TCP connection.



Ethernet wiring diagram

4.Specification

Overall Specifications	
Product Weight	1076g
Product Dimensions	140*136*215.4mm
Input voltage	14.8V~25.2V
Dynamic current	1000~1500mA @ 16V
Power consumption	Average 16W, Max 24W
Working environment temp.	-20℃ ~ +50℃
IP Rating	IP4X
Video Output (optional)	Micro HDMI(1080P 30fps/60fps) / Ethernet： IP (RTSP/UDP 720p/1080p 30fps H264/H265)
Local-storage	TF card (Up to 256G,class 10, FAT32)
Picture storage format in TF card	JPG(1920*1080)
Video storage format in TF card	MP4(1080P@30fps)
Control method	PWM / S.BUS / UART (TTL) / TCP / UDP
Gimbal Spec	
Mechanical Range	Pitch/Tilt:-40°(Up)～130°(Down), Yaw/Pan: ±300° / ±360°*N (IP output version)
Controllable Range	Pitch/Tilt: -30°～125°, Yaw/Pan: ±290° / ±360°*N (IP output version)
Vibration angle	Pitch/Yaw: ±0.02°
One-key to center	√

EO Camera spec	
Imager Sensor	1/2.8" Sony CMOS Sensor
Picture quality	Full HD 1080 (1920*1080)
Effective pixel	2.13MP
Lens optical zoom	40x, F=4.25~170mm
Digital zoom	x32
Field of View (D, H, V)	Wide: 73.80° / 66.35° / 39.98° Tele: 2.16° / 1.90° / 1.11°
Min object distance	0.1 / 1.5 / 3.0 / 5.0 / 10.0 m
Min illumination	Color(1/30s, 79.5dB) : 0.01 lux , BW(1/30s, 79.5dB) : 0.002 lux Color DSS(1/1s, 79.5dB) : 0.001 lux , BW DSS(1/1s, 79.5dB) : 0.0002 lux
S/N ratio	more than 50dB
Focus	Auto / One Push / Manual
White balance	Auto
Shutter speed	1/1 ~ 1/30,000 sec
Exposure control	Auto / Iris. Priority / Shut. Priority / Manual
Backlight compensation	Yes
Auto ICR	Yes
Image Stabilizer	Yes
Defog	Yes

IR Thermal Imager Spec	
Focus Length	35mm
Horizontal FOV	12.5°
Vertical FOV	10°
Diagonal FOV	16°
Detective Distance (Man: 1.8x0.5m)	1458 meters
Recognize Distance (Man: 1.8x0.5m)	365 meters
Verified Distance (Man: 1.8x0.5m)	182 meters
Detective Distance (Car: 4.2x1.8m)	4472 meters
Recognize Distance (Car: 4.2x1.8m)	1118 meters
Verified Distance (Car: 4.2x1.8m)	559 meters
Working mode	Uncooled VOx long wave (8μm~14μm) thermal imager
Detector pixel	640*512
Pixel size	12μm
Focusing method	Athermal prime lens
NETD	≤50mK@25℃,F#1.0
Color palette	White hot,Black hot, Iron Red

Digital zoom	1x ~ 8x
Radiometric function(optional)	Thermometry measuring mode：point anywhere measurement, selected box measurement
	Thermometry range optional：-20℃~+150℃, +100℃~+550℃
	Thermometry accuracy: ±3℃ or +3% of reading (whichever is greater) @ ambient temperature -20℃~60℃
EO/IR Camera Object Tracking	
Update rate of deviation pixel	30Hz
Output delay of deviation pixel	<30ms
Minimum object contrast	5%
SNR	4
Minimum object size	16*16 pixel
Maximum object size	256*256 pixel
Tracking speed	±48 pixel/frame
Object memory time	100 frames
EO Camera AI Recognition Performance	
Targets type	Car and human
Simultaneous detection quantity	≥ 10 targets
Min contrast ratio	5%
Min target size	5×5 pixel

Car detection rate	≥85%
False alarm rate	≤10%

5.FAQ

Q1: Forgot the camera IP after changing it?

To restore the default IP (192.168.2.119):

1) Format a TF card to FAT32. (If it is already FAT32, formatting is not necessary.)

2) Copy the file ip_bak.txt to the root directory of the TF card.

3) Power on the gimbal and wait for 3 minutes, the IP address will automatically reset to 192.168.2.119.

4) Power off the gimbal.

5) Confirm that the file ip_bak.txt is disappeared from the card — this means the reset was successful.

6) Insert the card back and power on. The IP should now be restored to 192.168.2.119.

Q2: Does UA40T-35 support taking picture during video recording?

Answer: Yes.

Q3: How does UA40T-35 store photos and videos?

Answer: The photo resolution saved in the TF card is 1920 * 1080, and the video is 1080P30fps.