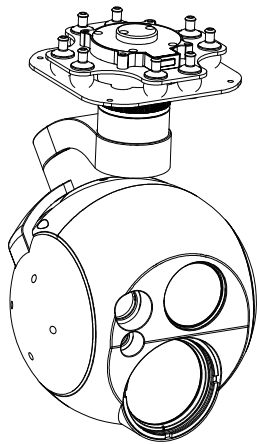
A30TR-50M
AI 30x EO + IR Dual-Sensor Laser Rangefinder Object Tracking Gimbal Camera

User Manual



For more details please scan the QR code or visit our website:
www.viewprotech.com

Disclaimer and Warning

Congratulations on purchasing your new Viewpro product. Please read this entire document carefully. Failure to read or follow instructions and warnings in this document may result in damage to your Viewpro product. Disassemble the gimbal camera by user is not permitted, as which may cause the camera does not work normally.

Viewpro accepts no liability for damage, injury or any legal responsibility incurred directly or indirectly from the use of this project. The user shall observe safe and lawful practices including, but no limited to, those set forth in the manual.

Legends



Warning



Important Note

Precautions

1. Please keep the camera in a dry environment to avoid fogging of the lens due to excessive humidity. If the lens is foggy, turn it on for a while and wait for the fog to dissipate.

2. The camera uses an infrared thermal imaging lens, please do not aim it at strong energy sources, such as the sun, laser beams, lava, etc. The temperature of the object observed by the lens must be less than 800°C, otherwise the camera will be burned and irreversible damage will be caused.

3. When cleaning the camera lens, be sure to use a soft and dry cleaning cloth to wipe the lens surface.

4. Do not touch the coating on the surface of the infrared lens directly with your hands or with hard objects, otherwise the coating will be damaged and the image will be blurred.

5. Do not plug or unplug the TF card when power on; after plugging and unplugging the TF card, please make sure that the TF rubber plug is tightly covered to prevent the power-on self-check from failing.

6. Please ensure that there isn't any obstacle while the motor rotating.

7. The pin insertion interface of control box cannot be connected with power supply in case the control board will be burned.

1. Product Introduction

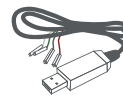
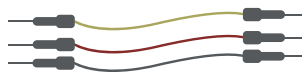
1.1 Introduction

A30TR-50M is a 3-axis triple-sensor AI gimbal camera for long range inspection and surveillance. It's powered by 30x optical zoom SONY RGB camera, 50mm 640*512 12 μm IR thermal sensor and 5km IR laser rangefinder(LRF).

A30TR-50M integrates powerful AI function, supports car and human auto detection and stable tracking. The simultaneous detection quantity of objects is more than 10. The RGB camera will perform auto-zoom to the ideal focal length for stable tracking while tracking a moving target continuously.

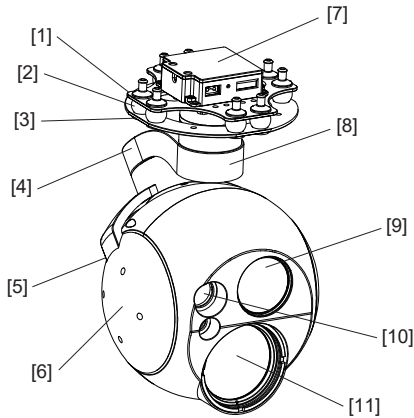
The precise LRF supports to measure the distance of targets within 5km (depends on environment and target size).

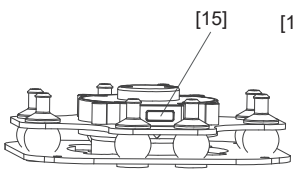
1.2 In the Box

Gimbal (Standard Version) ×1		Gimbal (Viewport Version) ×1	
Aluminum Cylinder ×4		USB to TTL line ×1	
M3 screw ×8			
Power Line ×1			
PWM Control line ×1			
Serial port/S.bus Control lin ×1			
Connect serial port line ×3			
Ethernet line ×1			

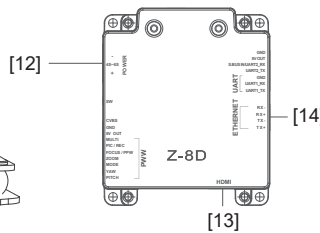
2.Installation Instruction

2.1 Overview





Viewport



Control Box

[1] Upper damping board
[2] Damping ball
[3] Lower damping board
[4] Roll axis motor
[5] TF card slot
[6] Pitch axis motor
[7] Control box
[8] Yaw axis motor
[9] FHD zoom camera
[10] Laser rangefinder
[11] Infrared thermal camera
[12] 4S~6S power interface
[13] Micro HDMI interface
[14] Ethernet interface
[15] Viewport unlock button



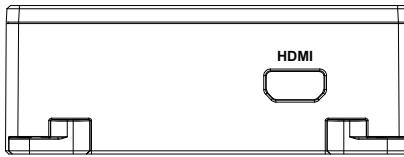
- Please ensure that there isn't any obstacle while the motor rotating.
- Please remove the obstacle immediately if gimbal camera is blocked during rotation.



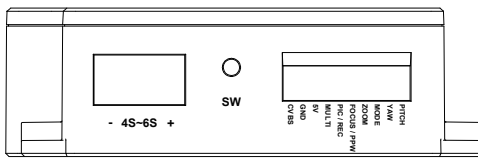
- Don't use laser ranging against glass within 5meters.
- Don't put the infrared thermal camera towards the sun, magma, laser, etc. in case any burn to the camera.

2.2 Control Box Printing

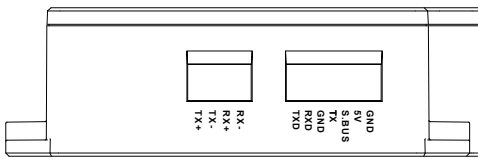
Front Side



Left Side

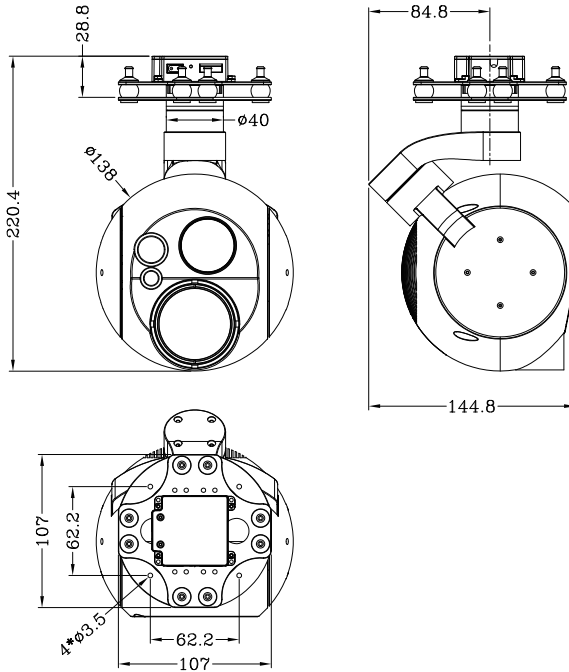


Right Side



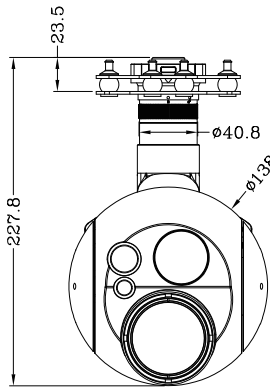
2.3.1 Device Dimensions (Standard Version)

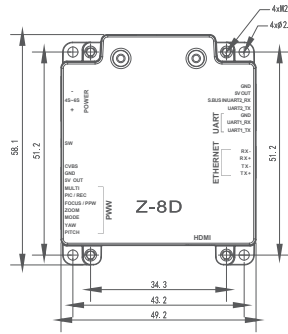
Unit: mm



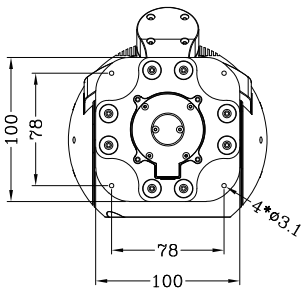
2.3.2 Device Dimensions (Viewport Version)

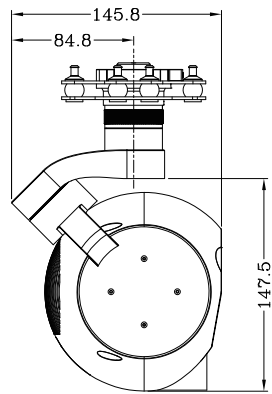
Unit: mm





Control Box



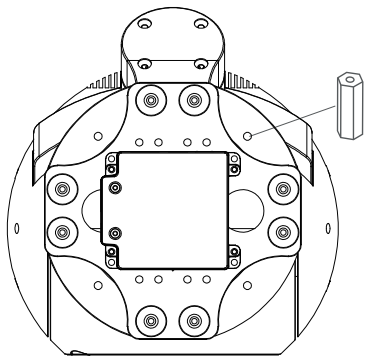


2.4 Install Mounting Part

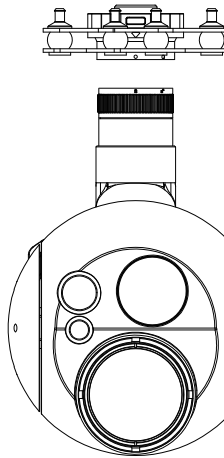
(1) Find out the arrow on the gimbal which indicating the yaw heading of the payload (i.e. the lens direction when the camera power on), and synchronize with the direction specified by the UxS.

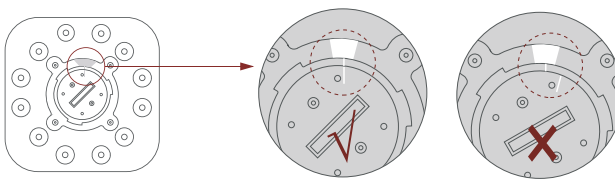
(2) Fix one end of the Aluminum Cylinder on the screw hole of lower damping board, and use M3 screw to fasten it.

(3) According to the provided screw hole dimension you can make suitable mounting holes on the UxS mounting board, and fixes the other end of the Aluminum Cylinder on the mounting board of the UxS (Viewport version is the same).

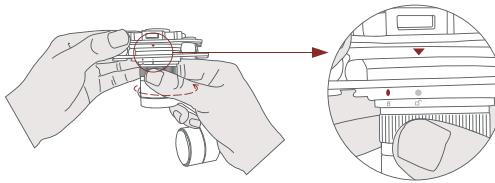


2.5 Viewport Release Instruction

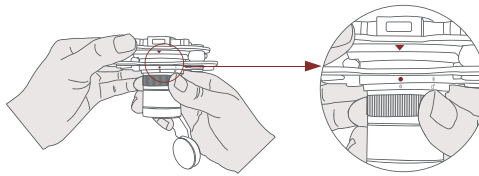




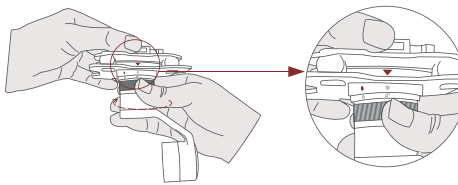
1. Make sure the two white stripes indicated in above picture are aligned with each other. (If the stripes are not aligned to each other, please pinch the connector part and turn it to left manually)



2. Align the white dot (unlock icon) to the red triangle (below unlock button), push the gimbal into the Viewport completely and then rotate the gimbal camera anticlockwise.



3. When you hear "click" sound (when red dot is aligned to the red triangle) means the gimbal camera and Viewport has been locked.



4. To unlock the Viewport, you need to press on unlock button and rotate the gimbal camera clockwise till the white dot align to the red triangle. Then pull the gimbal out from the Viewport.

2.6 Install TF Card

TF (Micro SD card):

Install the TF card to the card slot (Re. 2.1 Overview). Support max 256GB. Request Class 10 (10m/s) transmission speed or higher and FAT32 format.



- Make sure device is power off when inserting the TF card, hot plugging is not supported.

2.7 Image Output Interface

Description of all image output interfaces in the gimbal:
HDMI output: Micro HDMI port, supports 1080P@60fps, connects to external monitors or video transmitters for real-time preview.

Network output: Standard RJ45 port, supports RTSP/UDP/RTMP. Default: RTSP, stream at rtsp://192.168.2.119:554, 720P@30fps, 2Mbps bitrate . All parameters user-adjustable.

Analog output: not supported.



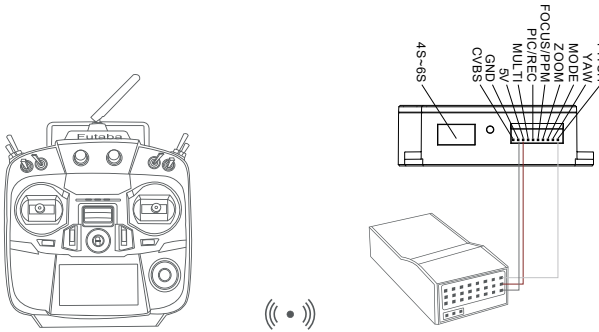
- Video output varies by model, refer to actual product. Due to 360° continuous yaw rotation, this gimbal series does not support HDMI. And SDI and HDMI are mutually exclusive and cannot be configured together on the same device.
- When using user interface software Viewlink for network connection, the network of external device (computer) should be the IP address: 192.168.2.2 (choose the last byte among 2~254, can not be 119 same as the gimbal), subnet mask: 255.255.255.0, Default gateway: 192.168.2.1, and all firewalls of the computer must be closed. Then enter the IP address of the gimbal camera, Open Video, the video stream can be outputted.

3. Signal Control

3.1 PWM Control

Control the gimbal camera functions by the multiplex pulse width modulation signal outputted by PWM channel of the remote control receiver. The camera needs up to 7 control channels of PWM. You can choose needed functions according to actual usage to reduce the required number of PWM channels.

3.1.1 PWM Connection Diagram (Connect pitch channel as an example)



Remote Controller

Receiver

3.1.2 PWM Control Operation Instruction

1) Pitch (PWM Pitch channel in to control Pitch. Joystick, rotary knob or 3-gear switch on remote control are optional. 3-gear switch as example.)



Position 1

Low Gear
Pitch Up



Position 2

Middle Gear
Pitch Stop



Position 3

High Gear
Pitch Down

2) Yaw (PWM Yaw channel in to control Yaw. Joystick, rotary knob or 3-gear switch on remote control are optional. 3-gear switch as example.)



Position 1

Low Gear
Yaw Left



Position 2

Middle Gear
Yaw Stop



Position 3

High Gear
Yaw Right

3) Mode (PWM Mode channel in to adjust speed control/one key to Home position etc functions. Rotary knob or 3-gear switch on remote control are optional. 3-gear switch as example.)



Position 1

Low Gear



Position 2

Middle Gear



Position 3

High Gear

Position 1: Low speed mode, control pitch / yaw with this mode at lowest speed
Position 2: Middle speed mode, control pitch / yaw with this mode at middle speed
Position 3: High speed mode, control pitch / yaw with this mode at highest speed

(If it is controlled by rotary knob, the speed will change according to switch position)

4) Function of continuous switching:

4-1) Operate 1 time continuously and quickly, from position 2 - 3, to Home position.

4-2) Operate 2 times continuously and quickly, from position 2 - 3 - 2 - 3, the camera lens looks vertically down.

4-3) Operate 3 times continuously and quickly, from position 2 - 3 - 2 - 3 - 2 - 3, to disable Follow Yaw Mode (gimbal yaw not follows by frame)

4-4) Operate 4 times continuously and quickly, from position 2 - 3 - 2 - 3 - 2 - 3 - 2 - 3, to enable Follow Yaw Mode (gimbal yaw follows by frame)

5) Zoom (PWM Zoom channel in to control Zoom. Joystick, rotary knob or 3-gear switch on remote control are optional. 3-gear switch as example.)



Position 1

Low Gear
Zoom Out



Position 2

Middle Gear
Stop Zoom



Position 3

High Gear
Zoom In

6) Focus (PWM Focus channel is to control PIP, IR color palette switch, 3-gear switch as example.)



Position 1

Low Gear
PIP switch



Position 2

Middle
Gear



Position 3

High Gear
IR color palette switch

Switch from Position 2 to 1: Picture in Picture. EO+IR , IR+EO, EO only, IR only.
Switch from Position 2 to 3: IR color switching: white hot, black hot, pseudo color

7) Pic/Rec (PWM Pic/Rec channel in to control take picture and record. Joystick, rotary knob or 3-gear switch on remote control are optional. 3-gear switch as example.)



Position 1

Low Gear



Position 2

Middle Gear



Position 3

High Gear

Switch from Position 2 to 1 to take a picture.
OSD display “IMG PHOTOING” at the left top corner and the picture is stored in TF card.

Switch from Position 2 to 3 to start “ Record ” , and repeat the operation to stop recording.
During recording, OSD display information of “REC 00 00 00”, as current recording time, and the remaining capacity of TF card. It will show the “TFXXXMB” when stop recording. When the storage capacity of TF card is full , “TF FULL” is shown on screen. If no TF card is inserted, “ NO TF” is shown on screen. Please insert the TF card before using.

8) Multi: tracking control



Position 1

Low Gear



Position 2

Middle Gear



Position 3

High Gear

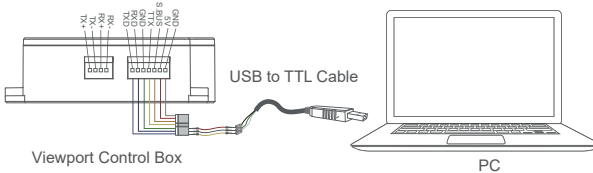
Switch from Position 2 to 1: (Reserved)
Switch from Position 2 to 3:
● Exit the tracking, display the cross cursor. Adjust the cross cursor to lock target object and start tracking
Switch from Position 3 to 2:
● Cancel tracking

3.2 Serial Port / TTL Control

TTL communication requirements: TTL signal is 3.3V, baud rate: 115200, data bit 8, stop bit 1, no parity, HEX send and receive.

Connection Diagram (PC - USB to TTL Cable- Gimbal Camera as example):

Gimbal Camera	**Cable**
TX ⟷	RX (White)
RX ⟷	TX (Green)
GND ⟷	GND (Black)



Connection Diagram

Diagram of USB to TTL Cable:

Connect the camera to the upper computer by USB to TTL cable (Adopt connection method of TX to RX, RX to TX, GNG to GND at Dupont ends of the provided USB to TTL cable, connect to the specified TTL of the gimbal, and the USB end of the cable connect to computer).

Install Viewlink control software to test the functions directly. Users may choose to develop their own software, please contact technical support for TTL control protocol file.

ViewLink is a user interface developed by Viewpro for Viewpro gimbal cameras, you can download it from Viewpro website (www.viewprotech.com) or ask distributors for installation package.

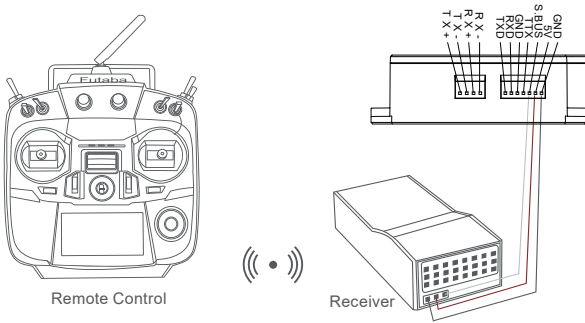
- Connect serial port of gimbal to pins, DO NOT connect with power supply.

- The default baud rate of serial port is 115200, which can be changed according to the docking equipment.

3.3 S.BUS Control

Control the gimbal camera functions by one combining signals. Connect the external S.Bus to S.Bus port on the control box, and the external S.bus signal GND connect to the GND interface of the control box.

Wiring Diagram (Take Futaba remote control for example):



Wiring Diagram

S.Bus control mode: default S.Bus signal channel 7-13 to control gimbal camera functions (the function of channel is consistent with the corresponding channel in PWM function description)

Channel 7: Yaw Control
Channel 8: Pitch Control
Channel 9: Mode Control
Channel 10: Zoom Control
Channel 11: Focus Control
Channel 12: Pic/Rec Control
Channel 13: Multi Backup



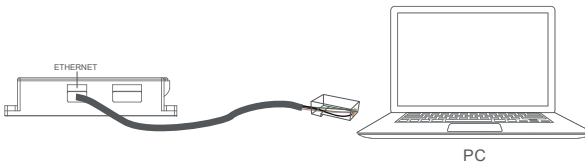
- User can set the channels by setting serial command according to the actual requirement. The S.Bus channel position can be arranged in any sequence within channel 7-13 to connect with the flight controller or remote control.

- TTL control and S.bus control cannot coexist at the same time for standard version. The defualt control is TTL if no requirement. The user can set to S.bus control if needed (please contact with our technical support for the setting instruction.)

3.4 TCP control

For Viewpro gimbal cameras with Ethernet output, the default IP address is: 192.168.2.119, control port: 2000. You can send the corresponding protocol to realize TCP control after connecting.

The TCP control protocol is [Frame header: EB + command ID: 90 + data body (serial port protocol) + Checksum (CS = body checksum, checksum is calculated as a sum of all bytes of data body modulo 256)]. Or directly use UI Viewlink to control after TCP connection.



Ethernet wiring diagram

3.5 Laser Rangefinder

A30TR-50M build-in infrared (IR) laser rangefinder (LRF). The target is the object in the center point of the screen.

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1. The LRF of A30TR-50M is default turned off to prolong life-span, can open It and choose ranging frequency in Viewlink main interface -LRF section manually.

2.If you don't use Viewlink, you can send below serial port commands

to set the laser rangefinder working methods:

- Single Use: 55 AA DC 05 1C 20 00 39
- Continuous ranging: 55 AA DC 05 1C 40 00 59
- Turn off again: 55 AA DC 05 1C A0 00 B9

3. Some cases might cause the distance show 0:

A. The distance is out of range

B. Target is too small to be ranged within the valid distance

C. The IR laser rangefinder can't get distance information from reflective objects (glass, water, rain) or over-inclined objects.

4.Specification

Hardware Parameter	
N.W.	1343g
Product meas.	145.8*138*218.2mm
Input voltage	14.8V~25.2V
Dynamic current	660~1250mA @ 16V
Power consumption	Average 10.6W, Max 20W
Working environment temp.	-20℃ ~ +50℃
IP rate	IP4X
Output	Micro HDMI(1080P 60fps) / IP (RTSP/UDP 720p/1080p 30fps H264/H265)
Storage	TF card (Up to 256G, class 10, FAT32 format)
Picture in TF Card	JPG(1920*1080)
Video in TF Card	MP4(1080P@30fps)
Control method	PWM / S.BUS / UART (TTL) / TCP / UDP

Gimbal Spec	
Mechanical Range	Pitch/Tilt: -55°(Up)～125°(Down), Roll: ±45°, Yaw/Pan: ±300° / ±360°*N (IP output version)
Controllable Range	Pitch/Tilt: -45°～120°, Yaw/Pan: ±290° / ±360°*N (IP output version)
Vibration angle	Pitch/Roll/Yaw: ±0.02°
One-key to center	√

EO Camera Spec	
Imager Sensor	1/2.8 Type STARVIS2 CMOS Sensor
Picture quality	Full HD 1080 (1920*1080)
Effective pixel	2.13MP
Lens optical zoom	30x, F=4.3~129mm, F1.6~F4.7
Horizontal viewing angle	64.0°(wide end) ~ 2.4°(tele end)
Digital zoom	12x (360x with optical zoom)
Min illumination	Color 0.009 lux (1/30 sec, 50%, High Sensitivity mode On) Color 0.09 lux (1/30 sec, 50%, High Sensitivity mode Off)
Recommended illumination	100 lx to 100,000 lx
S/N ratio	more than 50dB
Min object distance	10mm(wide end) to 1200mm(tele end)
Shutter speed	1/1s to 1/10,000s
Exposure control	Auto, Manual, Priority mode(shutter priority & iris priority)

White balance	Auto
Focus	Auto / Manual
Backlight compensation	Yes
Auto ICR	Yes
Image stabilization(EIS)	Yes
Defog	Yes
IR Thermal Imager Spec	
Focus Length	50mm
Horizontal FOV	8.8°
Vertical FOV	7.0°
Diagonal FOV	11.2°
Detective Distance (Man: 1.8x0.5m)	2083 meters
Recognize Distance (Man: 1.8x0.5m)	521 meters
Verified Distance (Man: 1.8x0.5m)	260 meters
Detective Distance (Car: 4.2x1.8m)	6389 meters
Recognize Distance (Car: 4.2x1.8m)	1597 meters
Verified Distance (Car: 4.2x1.8m)	799 meters
Working mode	Uncooled VOxlong wave (8μm~14μm) thermal imager
Detector pixel	640*512
Pixel size	12μm
Focusing method	Athermal prime lens
NETD	≤40mK@25℃, F#1.0
Color palette	white hot, black hot, pseudo color
Digital zoom	1x~8x

Camera Object Tracking	
Update rate of deviation pixel	30Hz
Output delay of deviation pixel	<30ms
Minimum object contrast	0.05
SNR	4
Minimum object size	16*16 pixel
Maximum object size	256*256 pixel
Tracking speed	±48 pixel/frame
Object memory time	100 frames
Laser Rangefinder	
Measure ability	≥5km for big target (eg. building) ≥3km for car（2.3m×2.3m ） ≥1.5km for people （1.75m×0.75m ） (Based on typical value: LOS visibility: ≥8km Diffuse reflection rate: ≥0.3 Humility: ≤80%)
Accuracy (Typical value)	≤ ±1m (RMS)
Wave length	1535nm pulse laser
Divergent Angle	≤ 0.5mrad
Measurement frequency	1~10HZ
Ranefinder	Measure the distance between the object at the center of screen and the laser rangefinder

Camera AI Performance	
Targets type	Car and human
Simultaneous detection quantity	≥ 10 targets
Min contrast ratio	0.05
Min target size	5×5 pixel
Car detection rate	≥85%
False alarm rate	≤10%

5.FAQ

Q1: Forgot the camera IP after changing it?

To restore the default IP (192.168.2.119):

1) Format a TF card to FAT32. (If it is already FAT32, formatting is not necessary.)

2) Copy the file ip_bak.txt to the root directory of the TF card.

3) Power on the gimbal and wait for 3 minutes, the IP address will automatically reset to 192.168.2.119.

4) Power off the gimbal.

5) Confirm that the file ip_bak.txt is disappeared from the card — this means the reset was successful.

6) Insert the card back and power on. The IP should now be restored to 192.168.2.119.

Q2: How to set the video storage format of A30TR-50M?

Answer: Supports 4K image storage and 4K 30fps video storage.

Q3: Does A30TR-50M support taking photos during recording?

Answer: Yes.